

# Verification of Input-bounded FIFO Machines

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# Table of Contents

1 Introduction

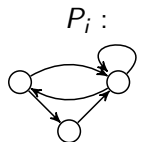
2 Branch-WSTS

3 Reachability

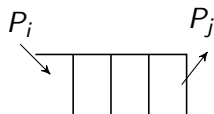
# FIFO Machines

Distributed processes such that

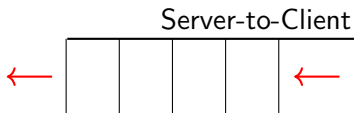
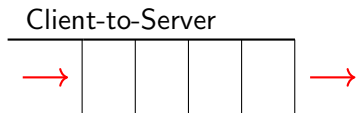
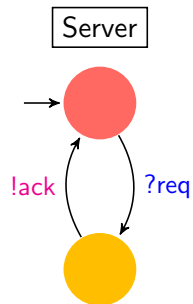
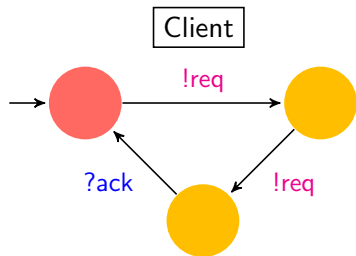
- each process is a finite state machine
- there are a fixed number of processes
- they communicate using queues



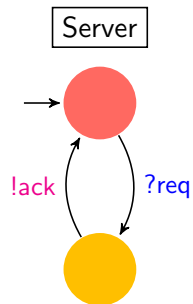
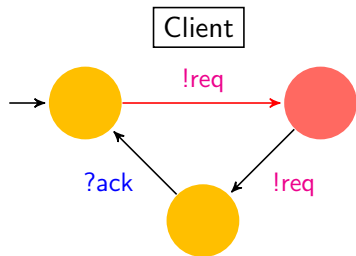
$P_1, \dots, P_n$



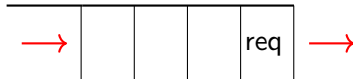
# Example



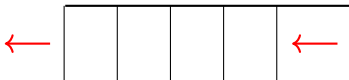
# Example



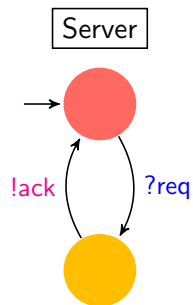
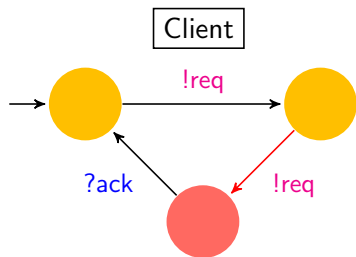
Client-to-Server



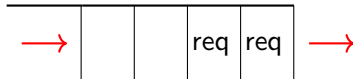
Server-to-Client



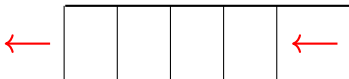
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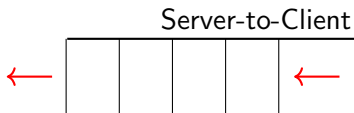
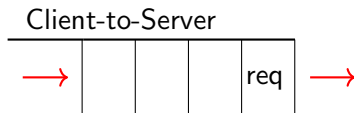
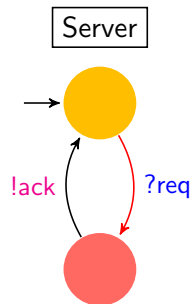
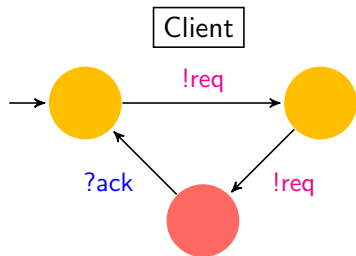
Client-to-Server



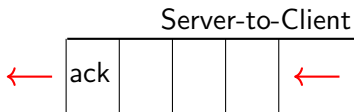
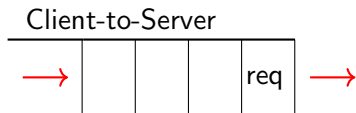
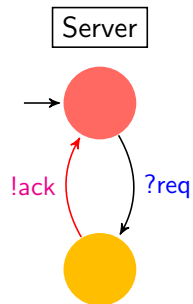
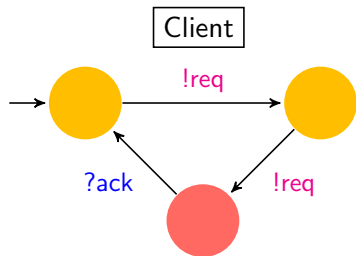
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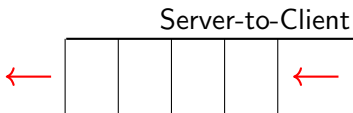
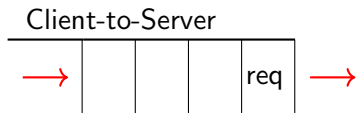
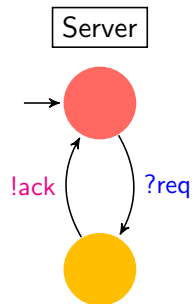
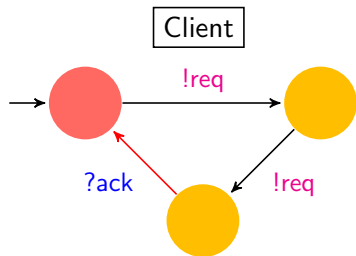


# Example





# Example



## Formal definition

A FIFO machine  $\mathcal{S}$  with one channel  $c$  is defined as  $\mathcal{S} = (Q, \Sigma, T)$  where

- $Q$  is a finite set of control-states,
- $\Sigma$  is the alphabet,
- $T \subseteq Q \times \{!, ?\} \times \Sigma \times Q$  is the transition relation.

The system is said to be in a configuration  $s = (q, w)$  when the control-state is  $q$  and the contents of the channel are  $w$ .

# Formal definition

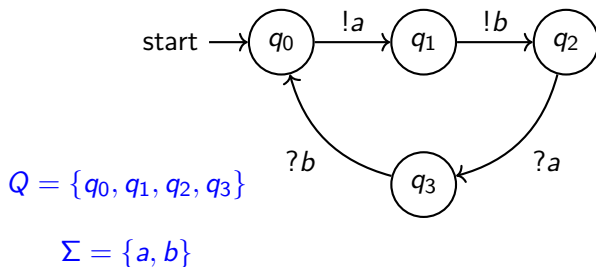


Figure: A FIFO system  $\mathcal{S}$  with initial configuration  $(q_0, \epsilon)$

# Verification problems

Give a FIFO machine  $\mathcal{S}$  with an initial configuration  $s_0 = (q_0, w_0)$ ,

- $\mathcal{S}$  **terminates** if it has no infinite run.

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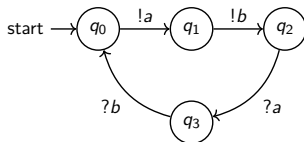
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## Note

Termination implies boundedness, but the converse is false.



$(q_0, \epsilon) \rightarrow (q_1, a) \rightarrow (q_2, ab) \rightarrow (q_3, b) \rightarrow (q_0, \epsilon) \rightarrow \dots$  is a non-terminating run.  
 $Post^*(s_0)$  is bounded.

# Verification problems











Give a FIFO machine  $\mathcal{S}$  with an initial configuration  $s_0 = (q_0, w_0)$ ,

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## Theorem

Testing the unboundedness of a channel in a general FIFO system is **undecidable**.<sup>1</sup>

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<sup>1</sup>Daniel Brand and Pitro Zafiropolo (1983). “On communicating finite-state machines”. In: *Journal of the ACM (JACM)* 30.2, pp. 323–342          

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- a configuration  $(q, w)$  is **reachable** if  $\exists \sigma$  such that  $(q_0, w_0) \xrightarrow{\sigma} (q, w)$ .



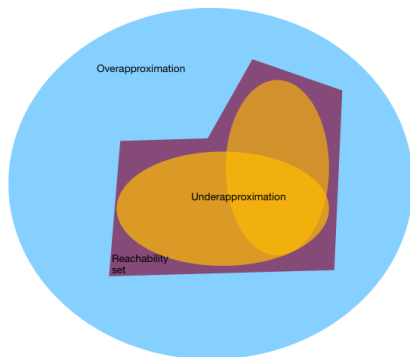
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- a **control-state  $q$  is reachable** if  $\exists \sigma$  and  $\exists w$  a channel valuation such that  $(q_0, w_0) \xrightarrow{\sigma} (q, w)$ .

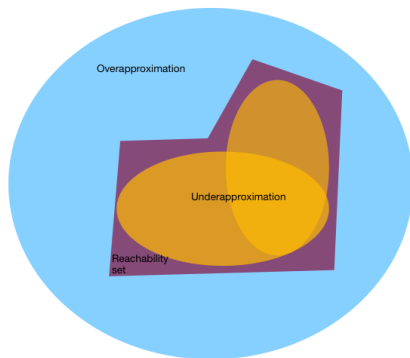
# Approach to verification

- Idea: to use over and under-approximations for verification



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- Idea: to use over and under-approximations for verification



- "Input-bounded FIFO systems" - an underapproximation

## Some subclasses of FIFO systems

The following subclasses have decidable properties.

- *Half-duplex systems* with two processes (but extension to three processes leads to undecidability). (Cécé and Finkel 2005)
- *Lossy FIFO systems*. (Abdulla et al. 2004)
- *Existentially-bounded deadlock-free FIFO automata\**. (Genest, Kuske, and Muscholl 2007)
- *Synchronisable FIFO systems\**. (Alain Finkel and Lozes 2017)
- *Flat FIFO systems* (most verification problems are in *NP*). (Alain Finkel and Praveen 2019)

# Input-bounded FIFO Systems

- *Bounded* language -  $L \subseteq w_1^* \dots w_k^*$ .
- *Input-bounded* -  $L_{send}$  is bounded.

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- *Reachability-bounded* - Channel contents belong to a bounded language.

## Theorem

A two-counter Minsky machine can be simulated by a reachability-bounded FIFO system.

# Table of Contents

- 1 Introduction
- 2 Branch-WSTS**
- 3 Reachability



# Well Structured Transition Systems (A. Finkel and Schnoebelen 2001)

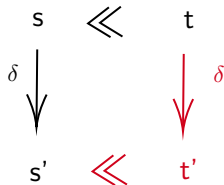
- A wqo over a set  $X \implies$  every infinite sequence  $x_0, x_1, x_2, \dots$  over  $X$  contains an increasing pair:  
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- Example
  - $\mathbb{N}$  over the ordering  $\leq$  is wqo.
  - $\mathbb{Z}$  over the ordering  $\leq$  is not. e.g.  $-1 \geq -2 \geq -3 \dots$  has no increasing pair.

# Well Structured Transition Systems (A. Finkel and Schnoebelen 2001)

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 $\exists i < j$  s.t.  $x_i \leq x_j$ .
- The transition system  $(X, \rightarrow)$  has strong compatibility i.e.

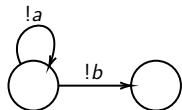


# Branch-WSTS

- $\mathcal{S} = (X, \rightarrow, \leq)$  is *branch-WSTS* if it is
- *branch-wqo*
  - if for every infinite run  $n_0(x_0) \rightarrow n_1(x_1) \rightarrow n_2(x_2), \dots$  of  $\mathcal{S}$ ,  $x_0, x_1, \dots$  is wqo.

# Branch-WSTS

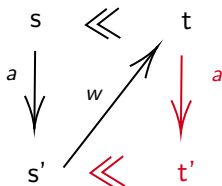
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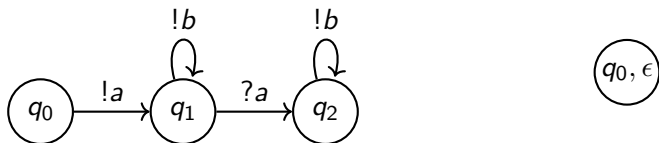
This FIFO system is branch-wqo under the prefix ordering but it is not wqo.

# Branch-WSTS

- $\mathcal{S} = (X, \rightarrow, \preceq)$  is *branch-WSTS* if it is
- *branch-wqo*
- *branch-compatible*
  - if for all configurations  $s, t, s'$  such that  $s \preceq t$  and  $s \xrightarrow{a} s' \xrightarrow{w} t$  implies that there exists a  $t'$  such that  $t \xrightarrow{a} t'$  and  $s' \preceq t'$ .

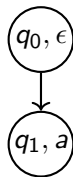
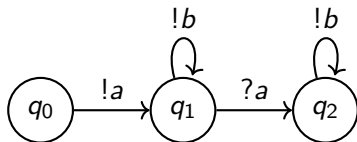


# Finite Reachability Tree<sup>1</sup>



<sup>1</sup>Adapted from A. Finkel and Ph. Schnobelen (2001). "Well-structured transition systems everywhere!". In: *Theoretical Computer Science* 256.1, pp. 63–92

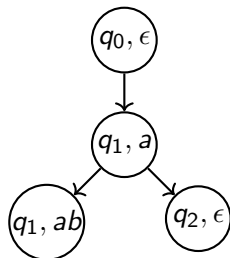
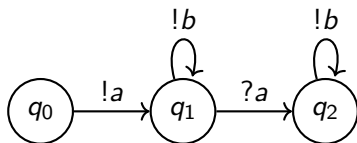
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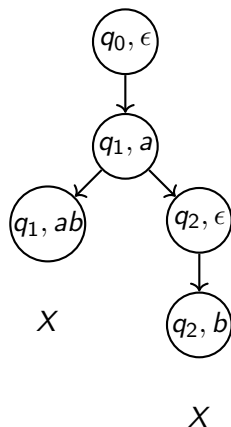
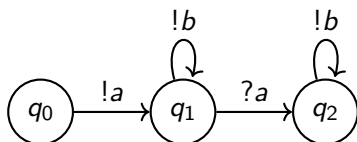
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X

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# Why branch-WSTS?

## Theorem

Boundedness and termination are decidable for branch-WSTS, if  $\leq$  is a decidable, partial ordering, and has computable successor.

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## Theorem

Boundedness and termination are decidable for branch-WSTS, if  $\leq$  is a decidable, partial ordering, and has computable successor.

## Proof sketch

- A branch-WSTS  $\mathcal{S} = (S, \rightarrow, \leq)$  has a finite reachability tree.
- Unbounded iff there exist two configurations in the finite reachability tree such that  $s_1 \xrightarrow{*} s_2$  and  $s_1 < s_2$ .
- Non-terminating iff there exists a subsumed node in the FRT.

# Input-bounded FIFO systems over the prefix-ordering

## Theorem

Input-bounded FIFO automata are branch-wqo for the prefix-ordering  $\leq_{pref}$ .

But they are not branch-compatible.

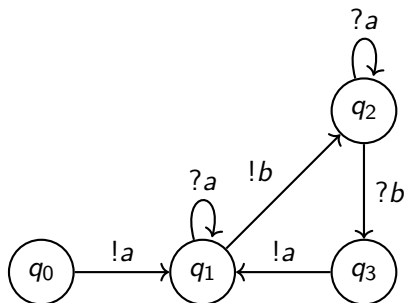


Figure: Consider  $\mathcal{S}$ , and configurations  $(q_1, \epsilon)$  and  $(q_1, a)$

## Prefix compatible relation

For two configurations  $s = (q, w)$ ,  $s' = (q', w')$ ,  $(q, w) \preceq_{comp} (q', w')$  if

- $(q, w) \leq_{pref} (q', w')$  and
- $\exists \sigma$  (with send and receive actions  $y_\sigma$  and  $x_\sigma$  resp.) such that  $s \xrightarrow{\sigma} s'$  and
- $x_\sigma = \epsilon$  or
- $|x_\sigma| \leq |y_\sigma|$  and  $x_\sigma^\omega = w.y_\sigma^\omega$ .

### Theorem

FIFO systems are branch-compatible for the relation  $\preceq_{comp}$ .

# Termination

- The prefix compatible relation is not an ordering.

## Theorem

Under this relation, we can construct a finite reachability tree for input-bounded FIFO systems.<sup>2</sup>

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<sup>2</sup>Thierry Jéron and Claude Jard (1993). “Testing for Unboundedness of FIFO Channels.”. In: *Theor. Comput. Sci.* 113, pp. 93–117

# Termination

## Theorem

Termination is decidable for input-bounded FIFO systems



# Table of Contents

- 1 Introduction
- 2 Branch-WSTS
- 3 Reachability**

# Reachability results

## Theorem

Reachability and control-state reachability are reducible to one another for input-bounded FIFO systems.

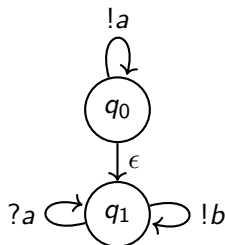
# Reachability of input-letter bounded systems

## Theorem

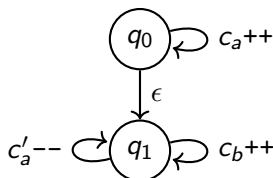
Control state reachability for input-letter bounded FIFO systems is decidable.

# Proof idea

Input-letter bounded FIFO systems can be simulated by counter machines with hierarchical zero tests.

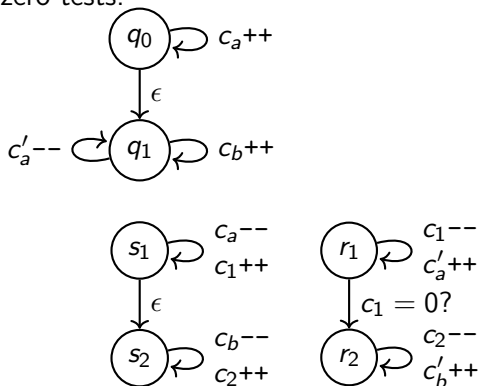


A FIFO machine  $S$ .



# Proof idea

Input-letter bounded FIFO systems can be simulated by counter machines with hierarchical zero tests.



Counter automata corresponding to the FIFO machine  $\mathcal{S}$ .

# Conclusion

System	Boundedness	Termination	Reachability
General FIFO systems	No [B83]		
Lossy Channel systems	Yes [A04]	Yes	Yes
Flat Systems	Yes [F19]	Yes	Yes
Reachability Bounded systems	No		
Input-bounded systems	Yes [J93]	Yes	?
Input-different-letter bounded systems	Yes	Yes	Yes [F87]
Input-letter bounded systems	Yes	Yes	Yes

Table: Verification problems

*Thank you!*  
*Questions?*

## Some additional information

- The half-duplex property for two machines and two channels (one in each direction) says that each reachable configuration has at most one channel non-empty.



- Abdulla, Parosh Aziz et al. (2004). “Using forward reachability analysis for verification of lossy channel systems”. In: *Formal Methods in System Design* 25.1, pp. 39–65.
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- Finkel, A. and Ph. Schnoebelen (2001). “Well-structured transition systems everywhere!”. In: *Theoretical Computer Science* 256.1, pp. 63–92.
- Genest, Blaise, Dietrich Kuske, and Anca Muscholl (2007). “On communicating automata with bounded channels”. In: *Fundamenta Informaticae* 80.1-3, pp. 147–167.
- Jéron, Thierry and Claude Jard (1993). “Testing for Unboundedness of FIFO Channels.”. In: *Theor. Comput. Sci.* 113, pp. 93–117.