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# Research Statement

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## Abstract

Asynchronous distributed processes communicating using First In First Out (FIFO) channels are widely used for distributed and concurrent programming. However, since they can simulate Turing machines, most verification properties are undecidable for them [BZ83]. Hence, there is a need to analyze subclasses which are powerful yet have decidable properties. The half-duplex restriction, introduced in [CF05], has been well-studied for the binary case, but there are a large number of open problems in the case of multiparty systems. Moreover, studying these systems in the ideal setting naturally leads to the question of their behaviour in unreliable settings. There are also various gaps in the existing literature regarding different notions of communication architecture. This proposal highlights some of the open problems that try to complete this picture.

## Background

Communication with asynchronous message passing is widely used in concurrent and distributed programs implementing various types of systems such as communication protocols [vB75], hardware design, designing and verifying session types [LY19], web contracts, choreographies, concurrent programs, Erlang, Rust, etc. An asynchronous message passing system is built as a set of processes running in parallel, communicating asynchronously by sending messages to each other via channels or message buffers. Messages sent to a given process are stored in its entry channel, waiting for the moment they will be received by the process. In general, sending messages is not blocking for the sender process, which means that the message channels are supposed to be of unbounded size. Moreover, asynchrony introduces a tremendous amount of new possible interleavings, which makes them difficult to analyse. In particular, when the channels are FIFO ordered, the verification of reachability queries is undecidable even when each of the processes is finite-state [BZ83]. This gives rise to the interest of studying underapproximations, which restrict the behavior of general FIFO systems in turn having decidable verification properties.

During the course of my PhD, I have analysed various such underapproximations. Firstly, we studied systems restricted to input-bounded runs (i.e. the sequence of messages sent through a particular channel belongs to a given bounded language). We show that there are various verification problems, most notably rational-reachability, which are decidable for such systems [BFS22a]. Secondly, inspired by the notions of synchronizability in [BEJQ18, GLL20, BB11], we study synchronizable systems (i.e. whether every execution can be rescheduled so that it meets certain criteria, e.g., a channel bound). For such systems, we provide a framework, that unifies existing definitions, and allows one to easily derive decidability results for synchronizability [BGF<sup>+</sup>21]. We also extend some notions for other communication architectures (peer-to-peer and mailbox). More recently, we

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also specifically studied the notion of synchronizable systems as in [BB11], and show that both, the problem of deciding inclusion to this class, as well as reachability problem, is undecidable for this class of systems. Finally, we also study an extension of well structured transition systems, originally studied in [Fin90], and show that boundedness and termination is decidable for this class of systems [BFS22b].

## Research proposal

I would like to focus my research in the near-future in the cusp of communicating (and communicating session) automata, choreography realisability, synchronizability, and verification in the presence of unreliability. The following excerpts summarize some of the main problems.

**Half-duplex multiparty communication.** In [LV11], the authors show that for channel contracts, which are naturally modelled as communication automata, the question of reliability is best described using the idea of half-duplex communication. However, they do not extend their notion to multiparty automata, but instead only study binary half-duplex systems. One of the problems to be studied in the immediate future would be using extensions of half-duplex behaviour, for example as in [GGL21], and extend the define of reliable contracts for the multiparty case. This will also be a relevant problem in the area of session types as communication contracts are often based on multiparty session types.

**Inclusion of  $k$ -MC into the synchronisability framework.** In [LY19], the authors define the notion of  $k$ -multiparty compatibility ( $k$ -MC) in order verify communicating session automata. This notion is of immense practical importance as it can be used to represent session types and interactions. Moreover, the notion of  $k$ -MC can be seen as comparable to some notions of synchronizability, and hence, it would be of interest to see if it can be expressed in the unifying framework defined in [BGF<sup>+</sup>21]. Furthermore, the notion of  $k$ -MC in the presence of unreliability is also an interesting open question.

**Practical implementation of verification of communicating systems.** The authors provide in [LY19] a tool that takes a system of communicating automata and a bound, and verifies if the system validates the  $k$ -MC property. This tool not only helps in  $k$ -MC checking, but also gives a practical procedure to check existential  $k$ -boundedness. In the larger context, there is a huge gap for tools which can be used to analyse communicating automata. Hence, a mid-term objective would be to add more capability to the  $k$ -MC checking tool in order to capture more properties to be verified. Moreover, it would be interesting to study if the notions of  $k$ -MC can be extended beyond session automata to communicating automata at large.

## Conclusion and long term objectives

The problem of verifying communicating automata is a difficult problem. Hence, the study of models to make their verification easier is ever-evolving. Very recent

works [GGL21, SZ22] have built on existing models in order to capture more subclasses of systems. It would be interesting to see if other known restrictions can be extended to communicating automata (e.g. reversal boundedness, ordering between channels, etc). Another open field of study would be regarding safety properties on these classes of systems, in particular properties studied in approaches based on session types [HYC16, DY12, SY19]. Moreover, due to the complexity of representing and analysing communicating automata, there has been a dearth of practical tools to verify them. On the other hand, their correspondence with multiparty session types is the foundation for various tools on session types. A worthwhile long-term goal would be to investigate if some ideas from the field of session types can be adapted to communicating automata in general. It would also be interesting to see how the graphical notions of Message Sequence Charts (MSCs) and High Level MSCs (HMSCs) can be exploited to gain more understanding of subclasses of communicating automata.

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